

UAVSAR Instrument: Current Operations and Planned Upgrades

Yunling Lou¹, Scott Hensley¹, Roger Chao¹, Elaine Chapin¹,
Brandon Heavey¹, Cathleen Jones¹, Timothy Miller¹, Chris
Naftel², and David Fratello²

¹Jet Propulsion Laboratory
California Institute of Technology
Pasadena, California

²Dryden Flight Research Center
Edwards, California

NASA Earth Science Technology Forum
21-23 June, 2011
Pasadena, California



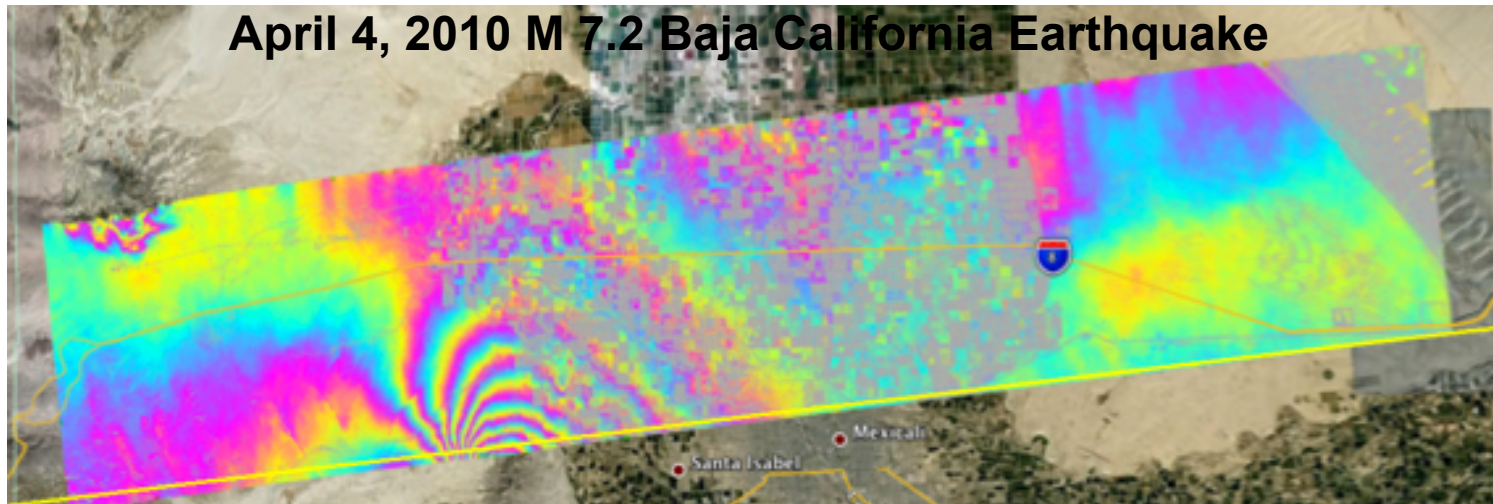


UAVSAR

Project Scientist: Scott Hensley, Project Manager: Yunling Lou



April 4, 2010 M 7.2 Baja California Earthquake



First earthquake deformation captured by UAVSAR using data acquired on October 21, 2009 and April 13, 2010

FY2010 Flight Summary

- 81 flights
- 412 flight hours
- 841 data lines
- 20 TB raw data
- Countries visited: Canada, Haiti, Dominican Republic, Costa Rica, Panama, Guatemala, Honduras, Nicaragua, El Salvador, USA
- Event response: Haiti and Mexicali Earthquakes, Gulf Coast oil spill

Event Response Capabilities

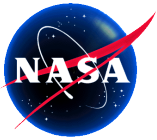
- Earthquake, wild fire, flooding, hurricane damage, volcano

Current Capabilities

- L-band repeat-pass polarimetric interferometry enabled by electronically scanned antenna and precision autopilot that can repeat tracks to within a 10 m tube
- Applications include surface deformation for solid earth, cryospheric studies, vegetation mapping and land use classification, archeological research, soil moisture mapping, geology and cold land processes.

Future Capabilities

- L-band single-pass polarimetric interferometry for topographic mapping and vegetation structure study
- P-band polarimetry for subsurface soil moisture and forest biomass measurements
- Ka-band single pass interferometry for arctic ice study






UAVSAR Coverage of CA Faults



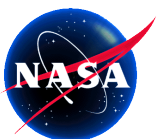
 UAVSAR Coverage

Faults by age of last movement

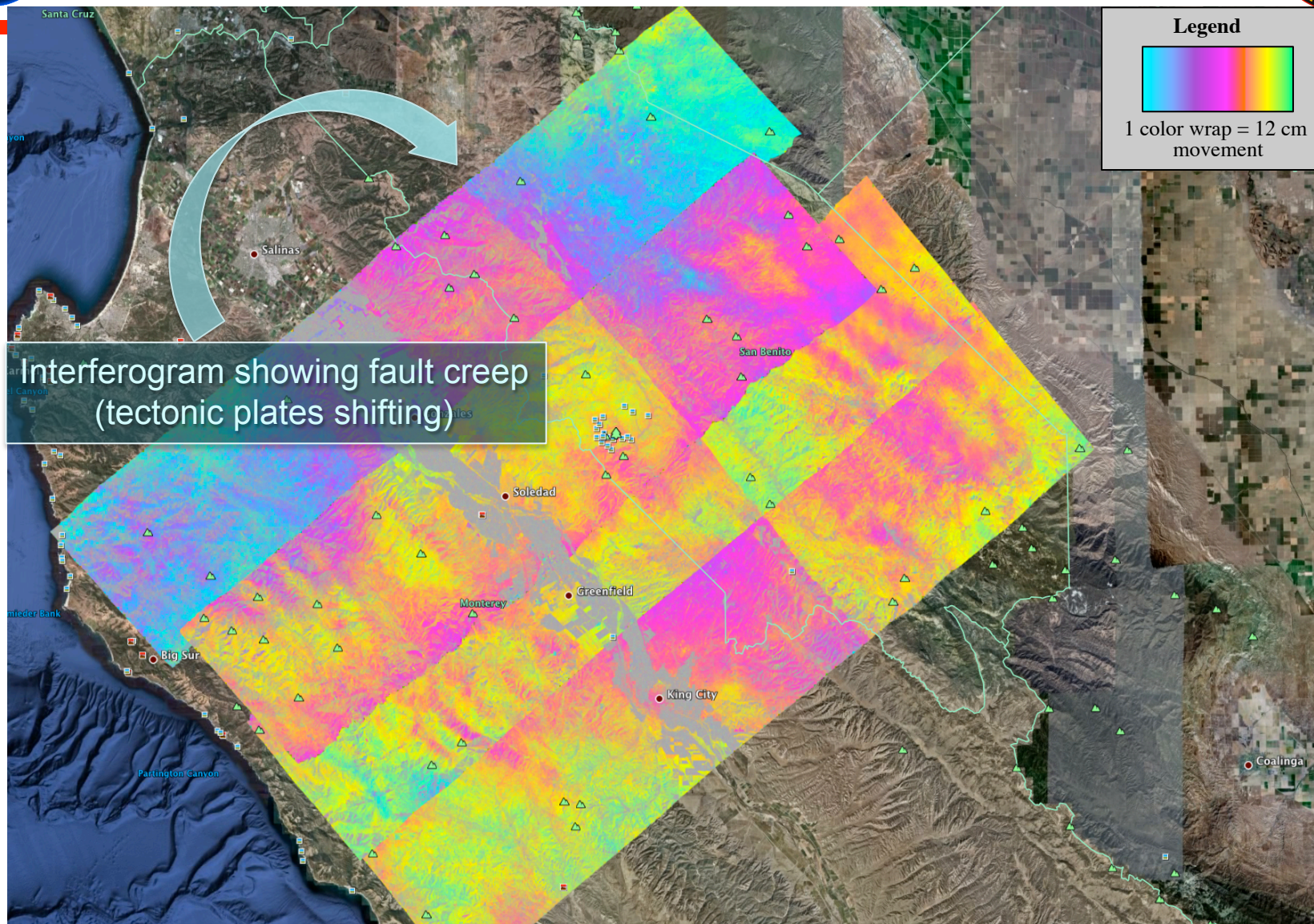
-  < 150 years
-  < 15,000 years
-  < 130,000 years

Main Faults Studied

- San Andreas Fault
- Hayward Fault
- Inglewood Fault
- San Jacinto Fault
- Elsinore Fault



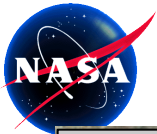
San Andreas Fault Monitoring



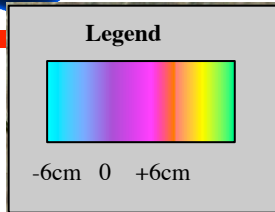
2009-10: San Andreas Fault, CA

UAVSAR

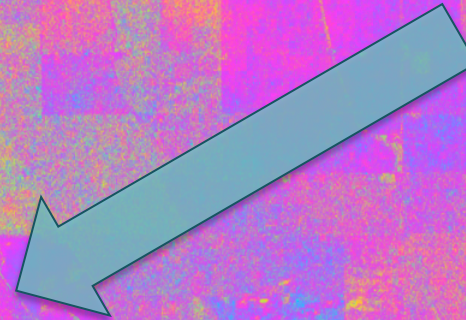
Note: deformation not absolutely calibrated as phase bias has not been removed from each image strip



Central California Subsidence Study



Interferogram showing subsidence (ground sinking) due to oil pumping



Missouri Triangle

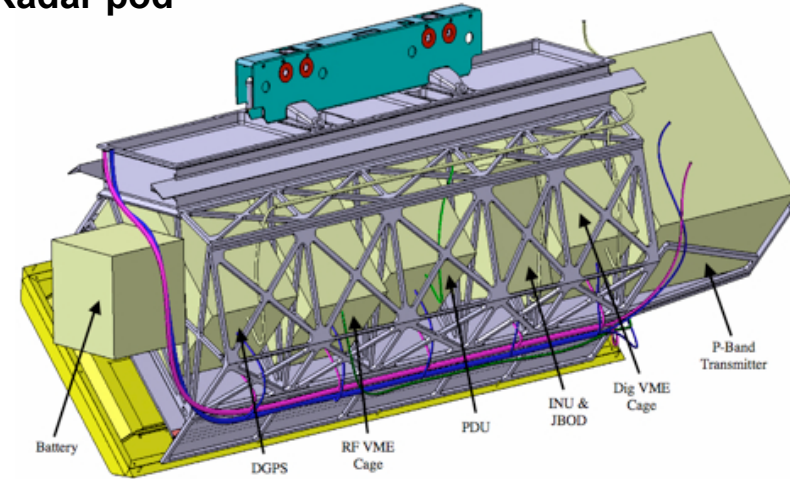
2010-09: Central California

UAVSAR

Current UAVSAR Configuration



Radar pod



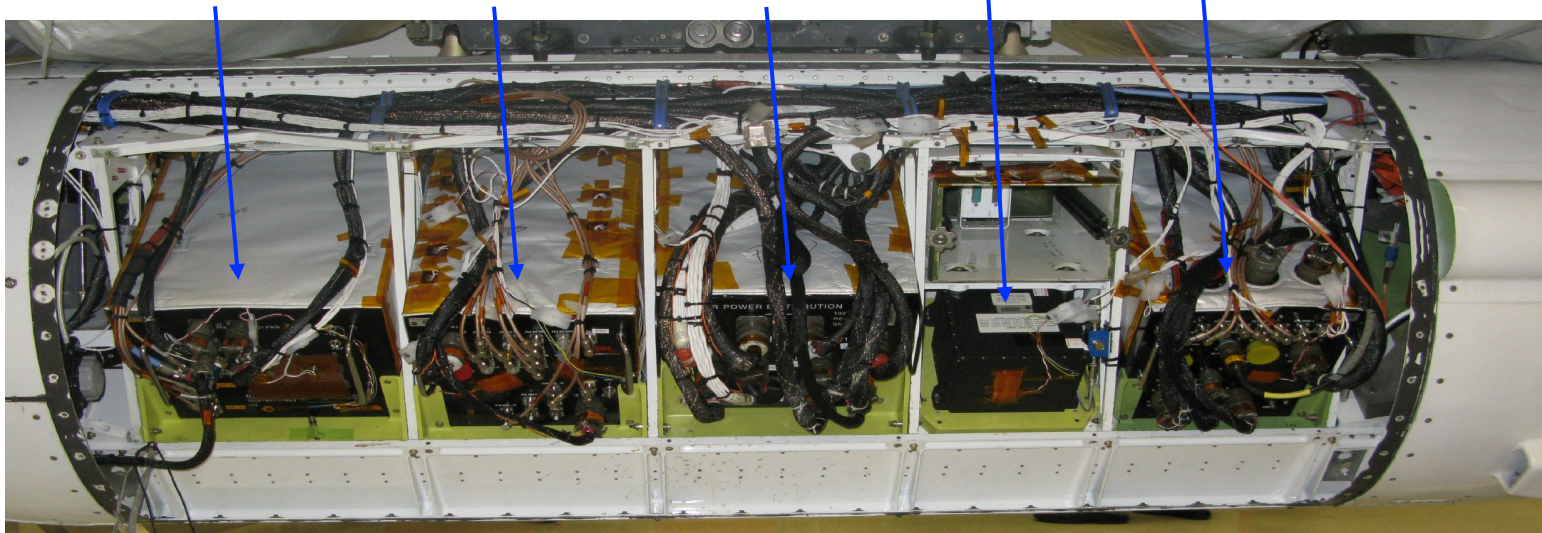
DGPS

RF

PDU

EGI

Digital Subsystem

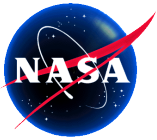




Key Radar Parameters



Parameter	Value
Frequency	L-Band 1217.5 to 1297.5 MHz
Bandwidth	80 MHz
Intrinsic Resolution	1.8 m Slant Range, 0.8 m Azimuth
Polarization	Full Quad-Polarization
Nominal Altitude (G-III)	12,500 m (41,000 ft)
Nominal Ground Speed (G-III)	215 m/s
Nominal Spatial Posting	6 m
Nominal Range Swath	22 km (POL SAR), 18 km (RPI)
Look Angle Range	25° - 65°
Noise Equivalent σ^0	< -50 dB



UAVSAR- Unmanned Airborne Vehicle Synthetic Aperture Radar



Multi-Frequency, Reconfigurable Imaging Radar Testbed



DC-8 based AIRSAR

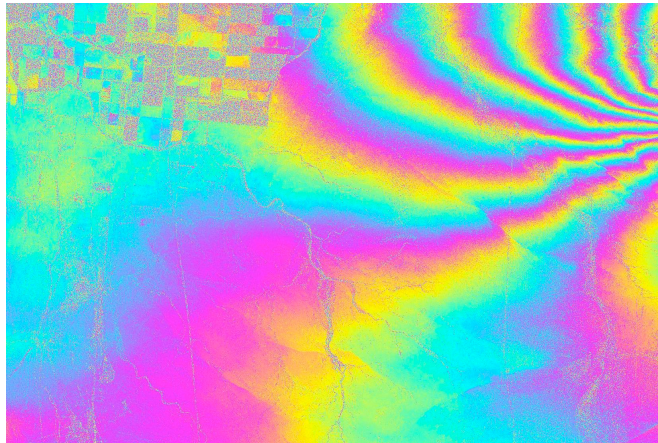


Gulfstream-III



Global Hawk

L-band repeat-pass interferometry



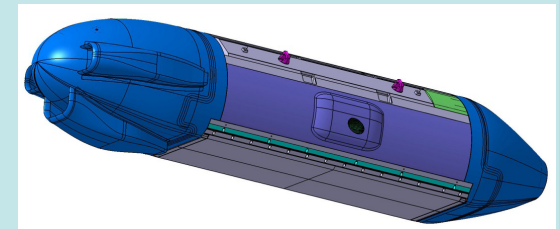
Mexicali earthquake deformation captured by UAVSAR using data acquired on October 21, 2009 and April 13, 2010. Major deformation (multiple color wraps) and subtle faulting are visible in the interferogram

Ka-band single-pass InSAR for observing glacier and land ice topography

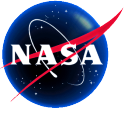


L-band single-pass PolInSAR

P-band POLSAR (AirMOSS) for measuring subsurface and subcanopy soil moisture



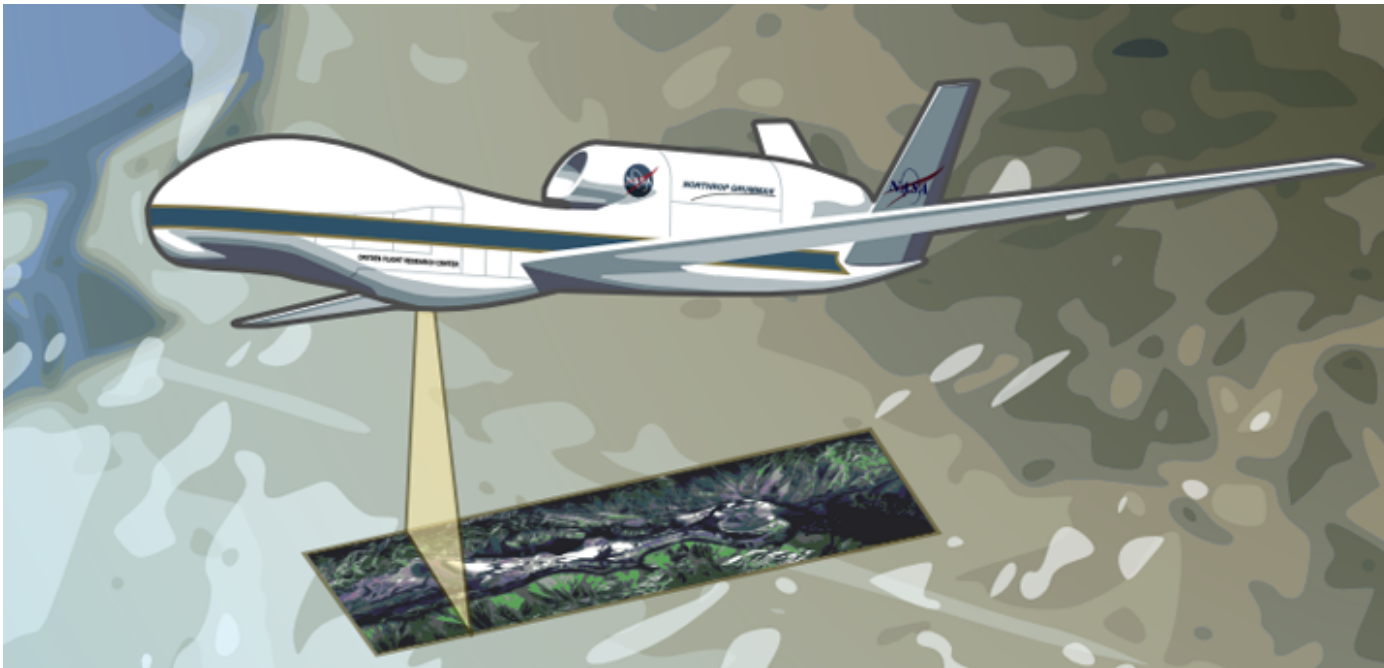
Ongoing Instrument Development



Update on UAVSAR Port To Global Hawk

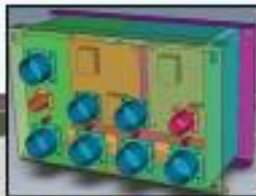


- Integrate the UAVSAR L-band radar to the Global Hawk UAV Bay 25
- Provide long range (~ 9000 nmi) to enable data collection of distant areas of interest without complicated deployments
- Study the ability of the Global Hawk to accommodate UAVSAR “Mini-Pods” under each wing to enable precision topographic maps and single pass polarimetric interferometry (SPI) providing vertical structure of ice and vegetation.





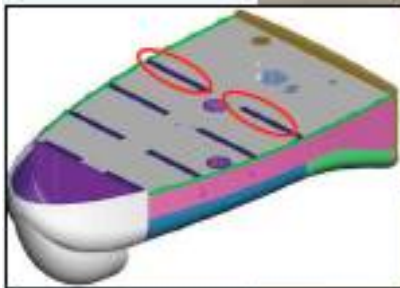
Payload Integration and Accommodations



Experiment Interface Panel & Ethernet Switch
(located throughout the aircraft providing power and communications)



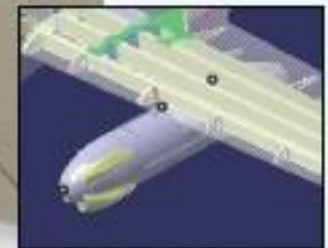
Payload Integration Software T&E



Mounting Rails



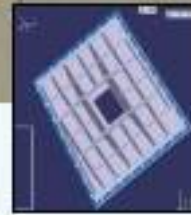
Bay Under the Nose



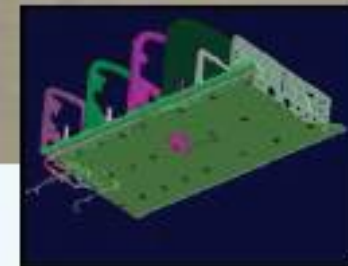
Wing Pods
(future capability)



Pallets and Hatches



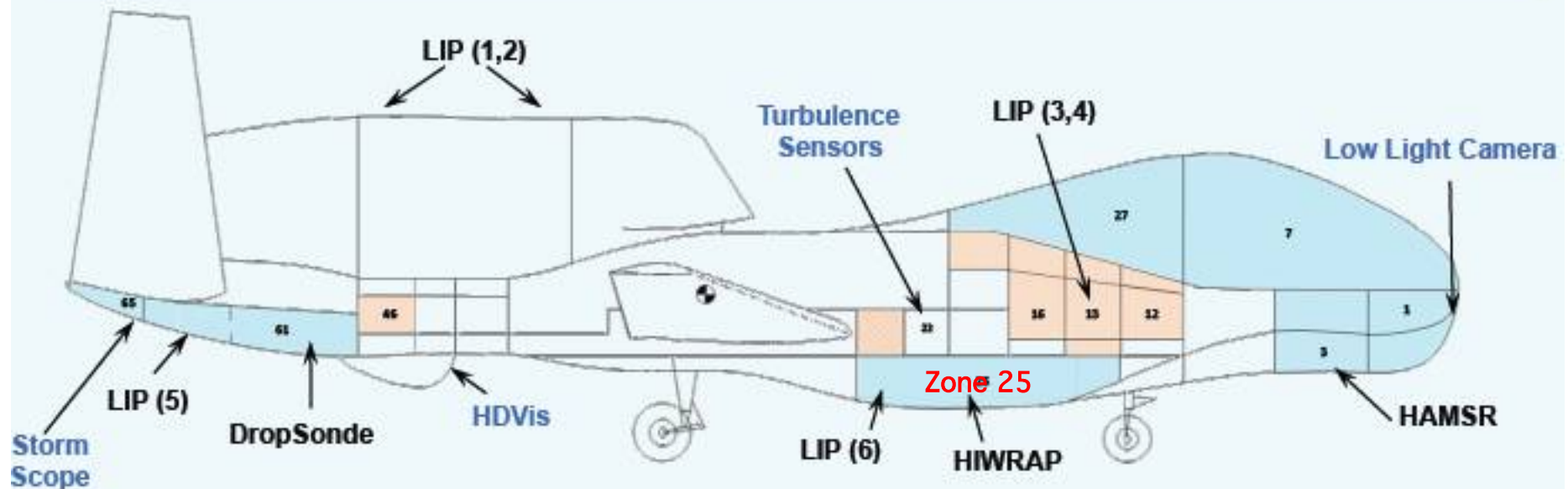
Zone 25



Mounting Hard Points



GRIP Instrumentation



HIWRAP - High Altitude Imaging Wind and Rain Profiler

DropSonde - NOAA DropSonde System

HAMSR - High Altitude MMIC Sounding Radiometer

LIP - Lightning Instrument Package

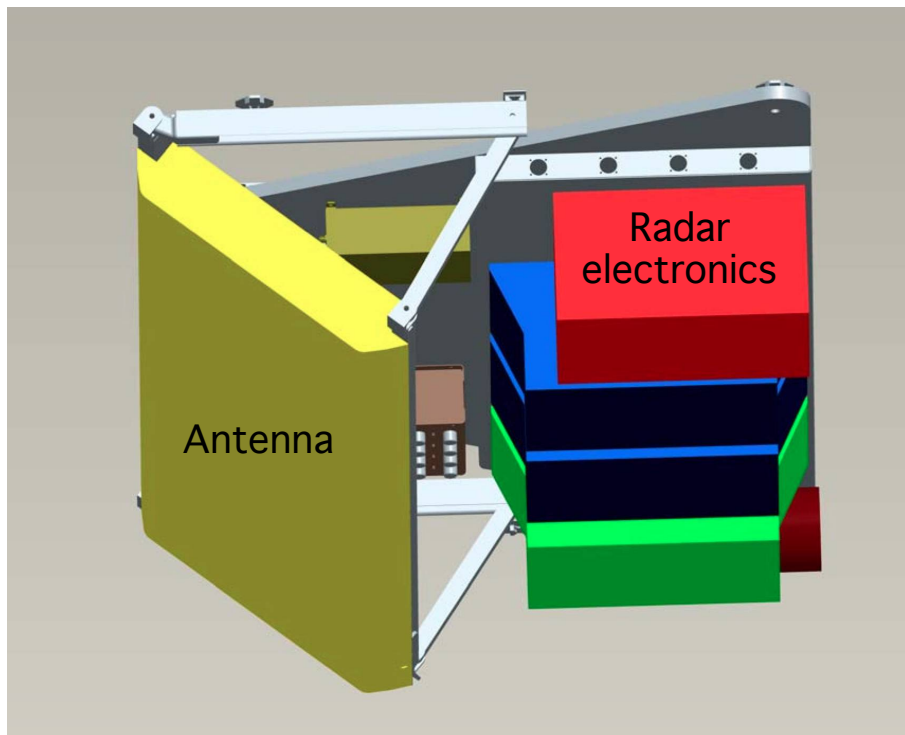
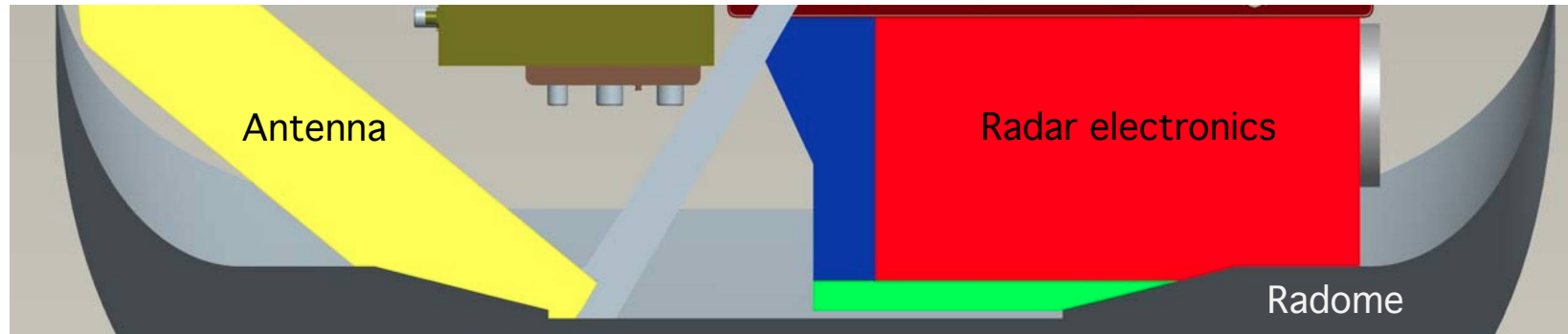
2 Cameras - HDVis and Low Light for Pilot Situational Awareness

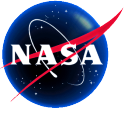
Storm Scope - Lightning Detection Display in the GHOC

Accelerometers - Real-time Turbulence Time-history Display in the GHOC



Instrument Accommodation in Zone 25





Global Hawk Implementation Steps



Install radar electronics and antenna from master pod to the GH fuselage (i.e. no wing pods)

- ☐ Relocate radar electronics into the GH fuselage (zone 25)
- ☐ Modify cable harnesses
- ☐ Rework thermal accommodation including air cooling of electronics
- ☐ Determine antenna performance with new radome (and cant angle)
- ☐ Design and fabricate a radome, either existing shape or new shape
- ☐ Design and fabricate mounting pallets and structure
- ☐ Install all components on aircraft
- ☐ Combined Systems Test
- ☐ Flight Tests in Edwards Air Force Base Range

If task plans are approved, will begin implementation immediately and plan for flight tests in November 2011.



P-band Radar Upgrade Overview



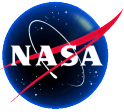
- Build a UHF SAR for root zone soil measurements which
 - Flies on the Gulfstream-III with the same mechanical and electrical interfaces as UAVSAR,
 - Fits in the UAVSAR pod,
 - Reuses as much UAVSAR electronics as possible,
 - Reuses the GeoSAR passive antenna design, and
 - Operates anywhere in the possible 280-440 MHz band since actual frequency allocation is uncertain.



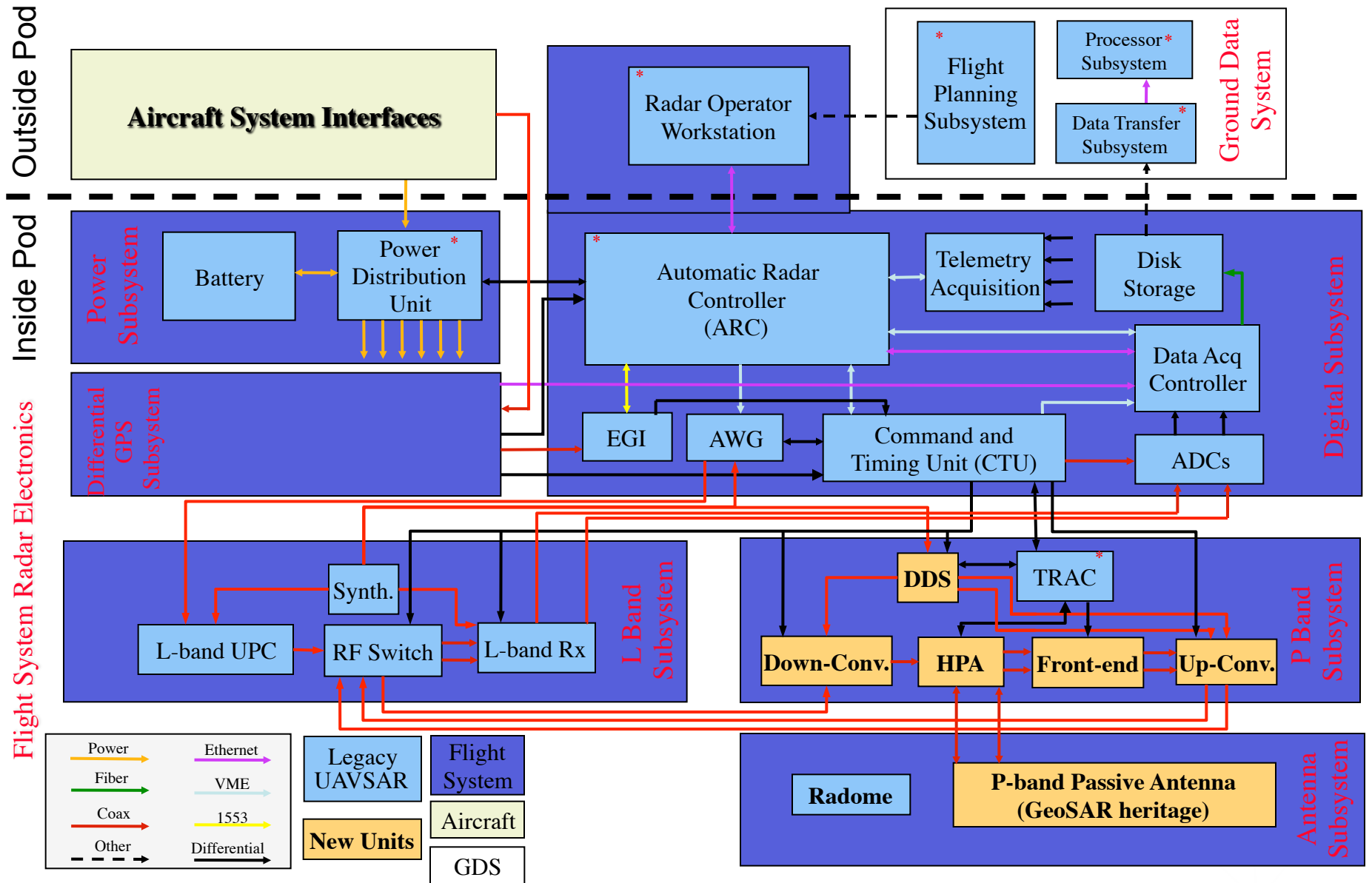
Hardware Highlights



- Reuse the UAVSAR L-band up converter and receiver so down convert from L-band to P-band to transmit and up convert from L-band to P-band on receive.
- Have bank of four filters (6, 20, 40, and 80 MHz) which can be switched in on a pulse by pulse basis to set the bandwidth.
- Use a Direct Digital Synthesizer (DDS) to allow us to change the center frequency on a pulse by pulse basis.
- Use a 2 kW High Power Amplifier (HPA) built by same vendor who built the GeoSAR P-band HPA.
 - Output power limited by need to fit in volume in pod.
- Antenna is 3% smaller than the GeoSAR UHF antenna in order to fit in the pod.



AirMOSS Electronics Block Diagram



*Requires S/W, F/W or H/W Changes



Current Implementation Status



- Conducting design reviews this month
- Major procurements are in place and prototype electronics build has begun
- Breadboard antenna was built and tested
- System integration and test will begin in late 2011 and flight testing is scheduled for March 2012
- Once the radar is flight tested and calibrated, will begin a 3-year campaign to measure root zone soil moisture over 9 North American biomes

